

Program:

09:00-09:10	Welcome and Presentation
09:10-09:50	"Aerial robots: From physical interactions to aerial robotic manipulation" Anibal Ollero, Universidad de Sevilla and Scientific Advisor of FADA-CATEC (Spain)
09:50-10:30	"Cooperation between aerial robots and unmanned underwater vehicles" Joao Soussa, University of Porto (Portugal)
10:30-11:00	Pause
11:00-11:40	"Cooperative multi robot aerial systems: applications and control" Tin Muskardin, DLR (Germany)
11:40-12:20	" Visual servoing for aerial manipulation" Vincenzo Lippiello, Università di Napoli (Italy)
12:20-13:00	"UAS-WSN cooperation for data collection in large environments" J. Ramiro Martinez-de Dios, Universidad de Sevilla (Spain)
13:00-13:25	Discussion with short presentations by attendants
13:25-13:30	Conclusions and Closing